# Paramount ME Homing Sensor Replacement and Troubleshooting

This document describes how to access and remove the Paramount ME's right ascension and declination axis homing sensors.

The Paramount ME's homing sensors work similarly to the optical sensors on automatic garage door openers. While a garage door is closing, a break in the light path of the optical sensor that is mounted near the floor causes the motor to reverse directions.

Likewise, as the right ascension and declination axes rotate during the homing process, a strip of aluminum machined into the mounts internal gearing breaks the homing sensor's optical path so that the control system knows the axis is at a fixed orientation, called the home position.

During the homing process, if the homing sensor on either axis is not functioning, the control system cannot find the home position and will continue slewing until a limit position is reached. At that point, the control system detects an error condition and begins to beep continuously.

Failure to locate the home position can be caused by:

- Any physical barrier, most commonly excessive grease after lubricating the mount, blocking the optical sensor. Remove the impediment by cleaning the homing sensor to restore functionality. See "Cleaning the Optical Sensor" on page 10 for details.
- The homing sensor cable connector becomes unseated or dislodged from the MKS 4000 main electronics board and must be reseated.
- Broken, damaged or shorted homing sensor wiring. The cables can be repaired, or a replacement homing sensor cable assembly can be purchased from the Software Bisque Store:

http://www.bisque.com/sc/shops/store/MKS4000HomingSensorCable.aspx

• Most uncommonly, the optical sensor fails and needs replaced.

## **Required Tools**

- 1 3/32 inch T-handle hex wrench
- 1 5/32 inch hex wrench
- 1 7/64 inch hex wrench
- 1 9/64 inch hex wrench
- 1 1/8 inch hex wrench
- 1 Needle nose pliers
- 1 Masking tape



Figure 1: Start with Paramount ME in this orientation.

Tighten the right ascension knob to free the RA axis (holding on to it!) and position it on one of the two hard stops as shown above. Back the RA knob off until the worm and gear are again meshed to hold it in place. This position ensures that the index on the gear will not interfere with the sensor.

# **Declination Motor Cover Removal**



Figure 2: Remove these five socket head cap screws.

Using a 5/32-inch hex wrench, remove the two 5/32-inch socket head cap screws in Figure 2. Using a 1/8-inch hex wrench, remove the three remaining socket head cap screws.

Removing the declination cover reveals the declination motor. At this point, we recommend also removing the back portion of the declination cover to make removing the declination motor assembly simpler.

Before proceeding, place a piece of masking tape over the cable access hole in the declination housing to prevent the socket head cap screws from falling inside.



Figure 3: Cover the cable access hole (inside the red circle on the photo) with masking tape to prevent screws from falling in.

Once the motor wire access hole is covered with tape, use the 3/32 inch T-handle wrench to remove the seven 3/8 inch socket head cap screws as shown in Figure 4.

Step 1: Rotate the declination axis balance knob fully clockwise to separate the worm from the gear.



Step 2: Remove the four socket head cap screws using a 3/32 inch T-handle hex wrench.

Step 3: Remove the 3 x 3/32 inch socket head cap screws using a T-handle hex wrench.

Figure 4: Removing the back portion of the declination worm block cover.

**IMPORTANT:** Rotate the declination axis balance knob fully clockwise to separate the worm from the gear. This also move the declination motor so you can access the four socket head cap screws that are located near the lower portion of the cover. When removing the socket head cap screws, while rotating the T-handle hex slowly be sure and apply downward pressure at the same time so the wrench does not slip.

When the cover has been completely removed, rotate the declination axis in either direction until a hard stop is encountered. By doing so, the mount's internal homing sensor index (that is part of the gear) is completely out of the way of the homing sensor.

The next step is to remove the two 7/64 inch socket head cap screws that mount the speed reducer to the worm block assembly as shown in Figure 5.



Figure 5: Removing the two screws that mount the speed reducer and declination axis motor to the worm block assembly.

Note the lower socket head cap screw has a washer, the upper screw does not. Please make sure to replace the screws in the correct holes during reassembly.

The lower screw fits into a slotted hole that allows the gear reducer to be rotated around a pivot point created by the upper screw. Rotating the assembly counterclockwise (as viewed in Figure 5) allows belt on the reducer's pulley to be easily removed. During reassembly, be sure to rotate the speed reducer fully clockwise (as viewed in Figure 5) about this pivot point to restore the original tension in the larger belt.

The declination axis motor and speed reducer can be placed on the top of the mount. Securing the assembly with masking tape is a good idea.

# **Removing the Declination Sensor**



Figure 6: Location of the declination axis homing sensor, looking toward the top of the declination axis from the bottom.



Use a standard hex wrench to remove the two socket head cap screws that are located near the flat surface of the declination housing (Figure 7).



Note the orientation of the sensor before removing the mounting screws!

Figure 7: Hex wrench used to remove socket head cap screws near the declination axis housing.

**IMPORTANT:** Maintaining the orientation of the homing sensor is critical. If the assembly is installed incorrectly (by rotating 90 degrees in either direction), when the declination axis rotates, the mechanical index on the gear will run into the side of the optical sensor and damage it.

Use a piece of tape, or permanent marker to scribe the correct orientation of the housing with in the axis. Here is a close up view of the sensor in the sensor housing.

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Figure 8: Define the orientation of the sensor housing by marking both the assembly and declination axis.

Once all four homing sensor mounting screws are removed, the next step is to remove the homing sensor assembly from the mount. The assembly fits very snugly and can be difficult to remove.

#### Do not pull in the homing sensor wiring to remove the homing sensor housing!

Insert the end of the needle nose pliers and orient them parallel with the long axis of the oval hole in the homing sensor housing. Use *outward pressure* on the needle nose pliers to capture the homing sensor housing (Figure 9) and extract it.



Figure 9: Use outward pressure on the needle nose pliers to carefully remove the sensor housing.



Figure 10: Close-up view of the optical homing sensor in the housing assembly.

Figure 10 show the two 5/64 inch button head cap screws that attach the optical sensor to the homing sensor housing. If you are replacing the homing sensors, remove both screws then rotate the optical sensor 90 degrees to remove it from the housing.

# **Cleaning the Optical Sensor**

The red arrow in Figure 10 marks the location of the optical path that must be clear of grease and other foreign matter for the sensor to function normally.

Before removing the homing sensor housing or the speed reducer, try using a can of compressed air to clear the optical path. Insert the compressed air's optional small plastic nozzle into the oval hole in the homing sensor housing and depress the release valve in short bursts, then test to see if homing is successful.

If this fails, completely remove the homing sensor housing and use an alcohol soaked cotton swab to clean between the posts marked by the red arrow in Figure 10.

#### **Right Ascension Axis Sensor Replacement**

The procedure for accessing and removing the right ascension homing sensor is similar to removing the declination sensor. Please carefully review "Removing the Declination Sensor" before proceeding.

The right ascension axis homing sensor sits behind the right ascension gear and must be accessed by removing one or both of the right ascension housing side panels.

This first step is to rotate the right ascension axis balance knob to separate the worm from the gear so that the mount swings freely. As always, use appropriate caution.

Next, see "Removing the RA and Dec Side Panels" in the Paramount ME User Guide: <u>http://www.bisque.com/sc/media/p/28169.aspx</u> for details how to remove the side panel.

If you wish to check the integrity of homing sensor cables or want to try cleaning out the right ascension axis' optical sensor with compressed air while troubleshooting homing failures (see "Cleaning the Optical Sensor"), first remove the panel on the RA housing box referenced in Figure 35 of the Paramount ME User Guide (this is the panel on the right side of the mount when looking at the Adaptor Panel).



Figure 11: Right ascension housing with the right panel removed. Follow the orange and yellow cable to locate the homing sensor.

If you plan to replace the homing sensor cable, remove both side panels. Having an incoming light source from both sides of the mount into the dark right ascension box is very helpful to those of us with older eyes. (If you're not yet 45, you may not understand.)

The yellow and orange homing sensor cable shows the way to the homing sensor housing (Figure 11).

Before performing more disassembly, when this panel is removed, try cleaning the optical sensor (page 10), then testing whether or not homing works.

To remove the right ascension homing sensor housing, in addition to removing the left panel on the right ascension housing, the lower side panel must also be removed to access and easily remove the speed reducer.



Figure 12: Remove the lower panel to access and remove the speed reducer.

Raise the mount's polar axis until the 1/8 inch socket head cap screws in the bottom of the lower side panel are aligned with the holes in the wedge. Remove all eight screws and remove the lower side panel. Note that passing the socket head cap screws through the holes in the wedge can be tricky. Try adding a small dab of heavy grease to the end of the hex wrench to give it more cohesion with the screw. If the screw falls off in between the wedge and the right ascension box, you'll need to fish it out from the inside "depressions" in the wedge.

With the lower panel removed, remove the speed reducer and motor assembly, then set it on the bottom of the right ascension housing. As with the declination motor assembly, make note of the slotted hole (on the top side here) and the pivot point (created by the bottom mounting screw).



Figure 13: Removing the two screws that mount the speed reducer and motor assembly.



Figure 14: The right ascension homing sensor housing is now accessible for cleaning, removal and replacement.

When the two sensor housings have been removed assemble the new sensors. Then the two units can easily be re-installed.



Figure 15: Homing sensors cabling with the homing sensors mounted to the homing sensor housings.

The homing sensors can now be installed by reversing the procedures described above.

See "Through the Mount Cabling" in the Paramount ME User Guide: <u>http://www.bisque.com/sc/media/p/28169.aspx</u> for details how to run the homing sensor cable and homing sensor up to the declination axis.

## **IMPORTANT ASSEMBLY NOTES:**

- Do not over tighten the two button head cap screws that hold the plastic sensor in the housing. Over tightening the two screws will deform the optical sensor. Also, tighten each evenly as opposed to tightening one completely, then the other.
- Remember that the sensor orientation is critical.
- The longer (teal colored) cable is for the declination axis homing sensor. Before mounting the homing sensor housing, this cable must be run through. In other words, you cannot install the declination homing sensor fully assembled as shown in Figure 10.